

# Virtual Vehicle Research

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Rail Research @ Virtual Vehicle

Department Rail

August 2026



A photograph of a modern, multi-story building with a vibrant red facade and large glass windows. The building is captured from a low angle, emphasizing its height. The sky is a clear, bright blue. A semi-transparent dark blue banner is overlaid across the middle of the image, containing the text "Virtual Vehicle Research" in white. The building's architecture features clean lines and a mix of red and glass materials. The windows reflect the sky and surrounding environment. The overall scene is bright and clear, suggesting a sunny day.

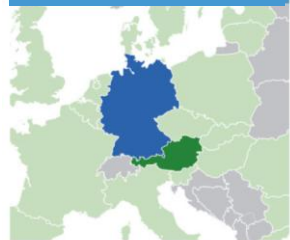
# Virtual Vehicle Research

# From the initial spark to a global player

## 2002-2007 Foundation

Initiation of a research center for **virtual vehicle development**

AUSTRIA &  
GERMANY



## 2008-2017 Structure & Growth

- R&D center for **sustainable mobility**
- Focus on EU projects and contract research

EUROPA+



**K2MOBILITY**  
SUSTAINABLE VEHICLE TECHNOLOGIES

## 2018-2026 / 2027-2034 Long-term stability & international success

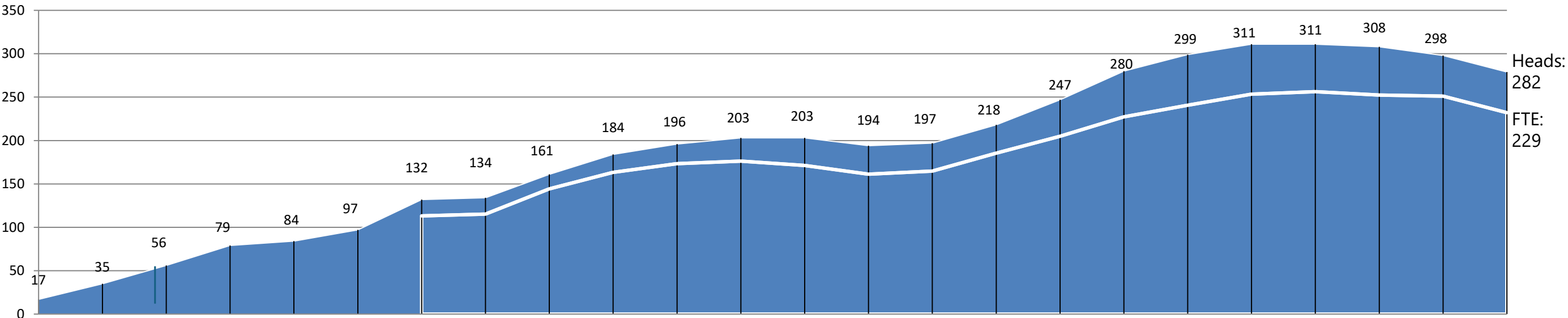
- Recognized international player
- Strategic partner for road and rail
- **Additional domains:** robotics, energy, health-tech, defense, ...
- Putting innovations from 300+ experts into practice

## WORLD-WIDE NETWORK



# Staff and Shareholders

Status: 31.01.2026



2002

2008

Additional Shareholder

2019

Additional Shareholders

**Graduate ratio: 90 %**

**130+ finished PhDs** at VIRTUAL VEHICLE (since 2008)

**40+ ongoing PhD** dissertations



**21 Nations**

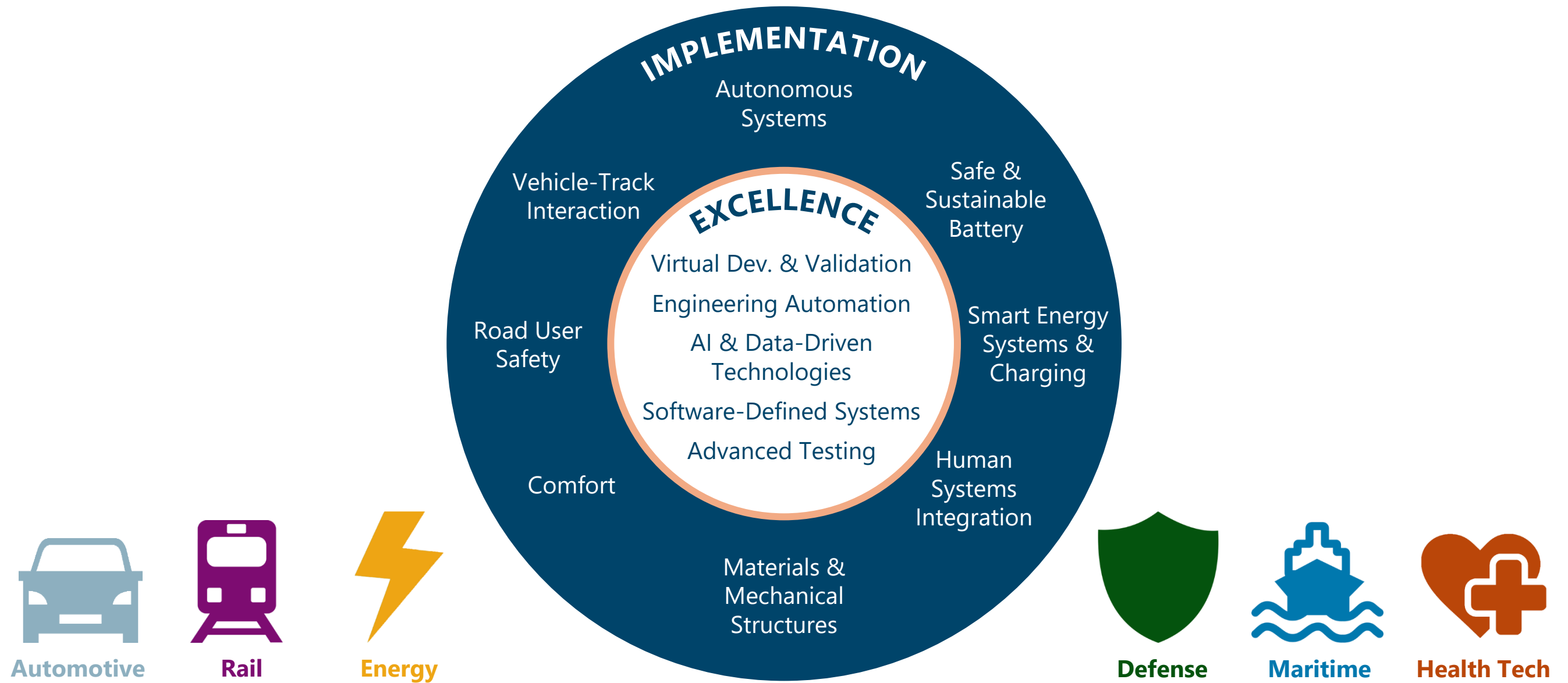
2021

Foundation 2021

2024

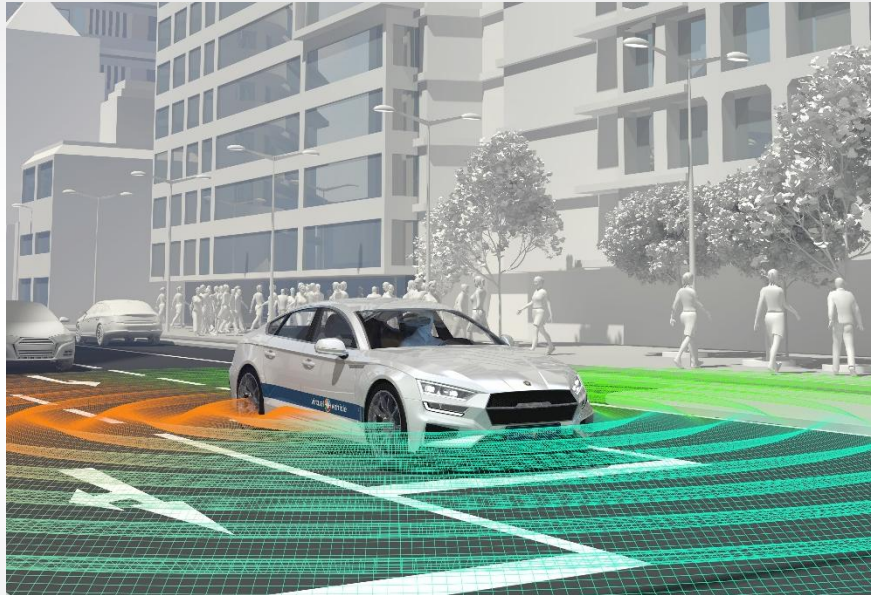
Spin-off 2024

# Fields of activities



# Bridge between science and industry

## COMET K2



- COMET K2 Digital Mobility
- Long term co-operative research
- Leveraging investment

## FUNDED PROJECTS



- 50+ ongoing EU projects
- 100+ completed EU projects
- International visibility and reputation

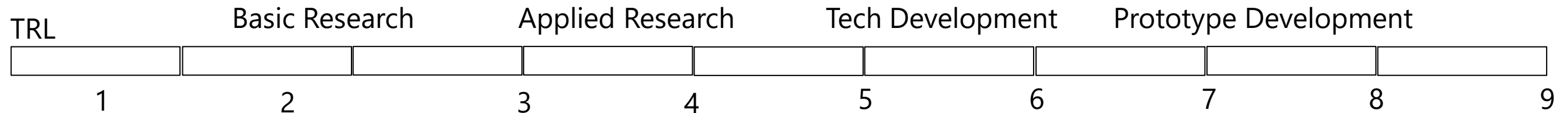
## CONTRACT WORK



- Research & development
- Test bed & demonstrators
- Industry agreements

# VIRTUAL VEHICLE - high performance ecosystem

Opportunities and competences for all maturity levels



PhD Cooperations



COMET K2 DM



Competence Centers for  
Excellent Technologies

EU-Joint Undertaking



FWF-funded Projects



Der Wissenschaftsfonds.

Strategic Projects

EU-funded Projects



FFG-funded Projects



Knowledge Transfer

- Bridge Program
- Living Innovation Lab



# Partner network

International industry and research network (excerpt)

## INDUSTRY



## SCIENCE



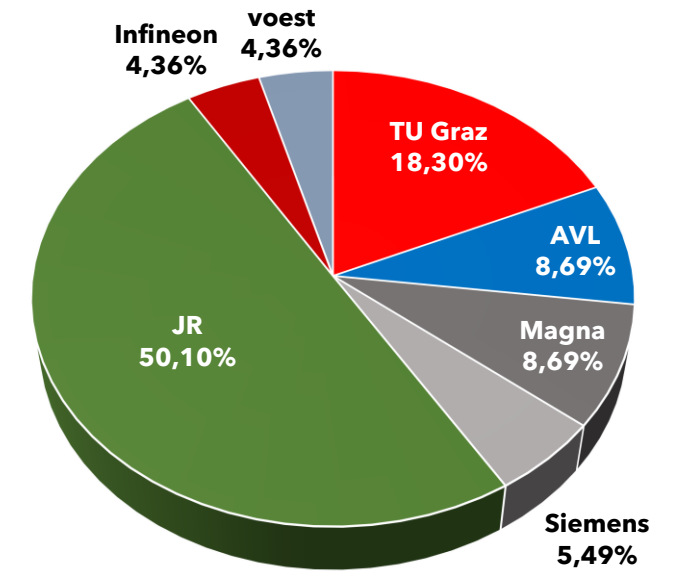
## RAIL-SPECIFIC



## HEALTH



## Shareholder



- 30+ MEUR turnover
- 180+ industry partners
- 80+ scientific partners

# Today, VIRTUAL VEHICLE is Europe's largest research center for virtual vehicle development



## Further domains



ENERGY



HEALTH TECH



MARITIME



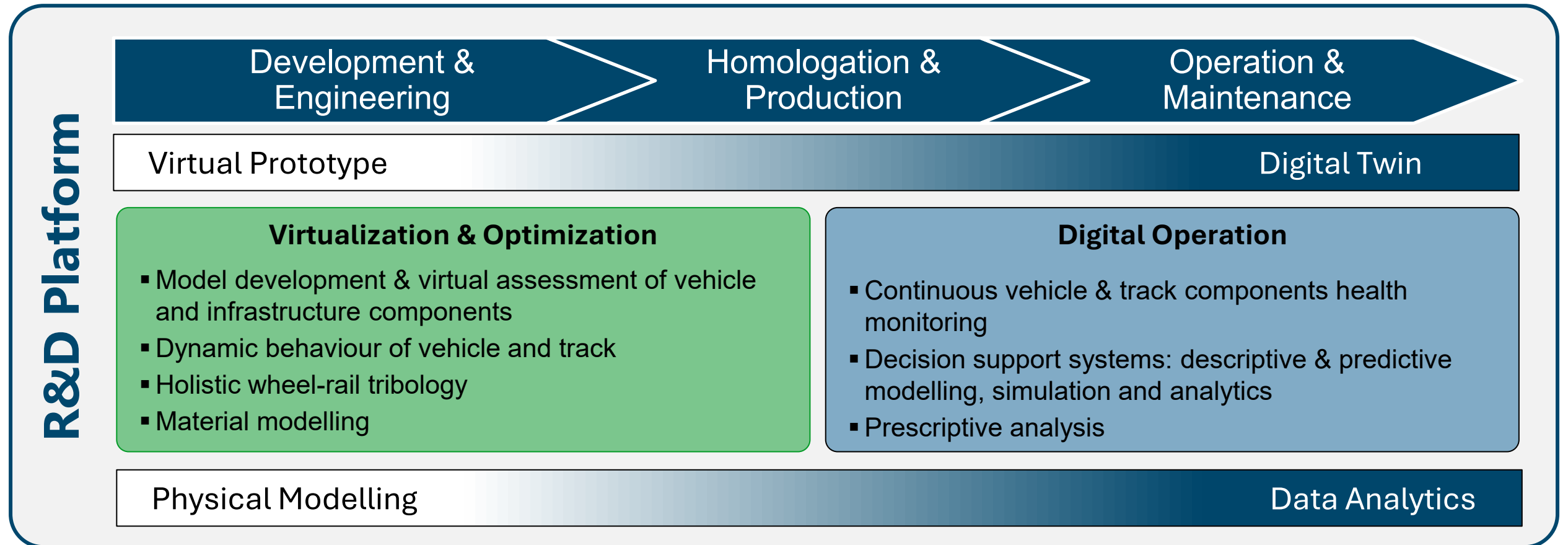
DEFENSE

# Vehicle-Track Interaction

# Overview

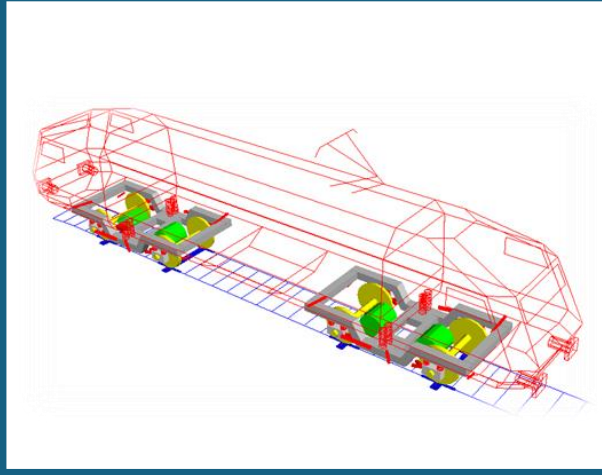
## Mission

Provide a **R&D platform** for de-risking **future rail system technologies**, by means of research and technology development with a focus on a service oriented, **modular virtual validation framework**.



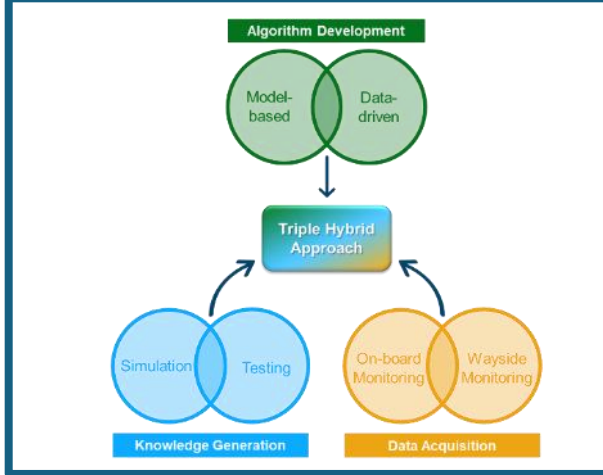
# Fields of Activity

## Vehicle Dynamics & Operation Analysis



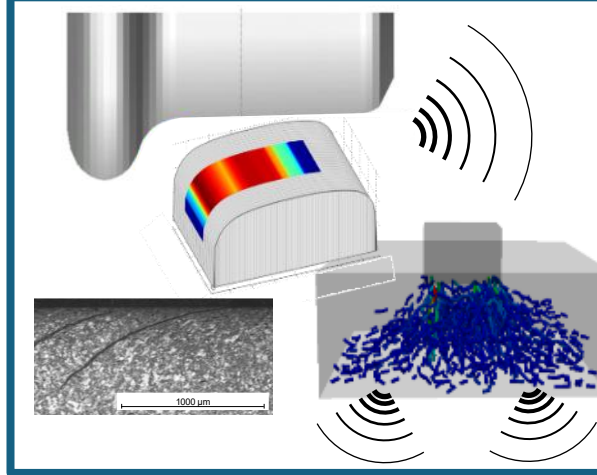
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- » Simulation and modelling of vehicle/track interaction
- » Vehicle and track parameter identification
- » Virtual homologation of running behaviour (EN 14363)
- » Probabilistic vehicle and track design

## Monitoring & Diagnosis



- » Profound context-based knowledge
- » Algorithm development based on hybrid approaches
- » Model-based and data-driven diagnosis and prognosis methods
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## Wheel-Rail Interaction & Deterioration Phenomena



- » Profound knowledge of physics
- » Modelling of complex interactions and phenomena
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- » Wheel/Rail surface damage
- » Wheel/Rail contact phenomena
- » Friction management
- » Track degradation
- » Noise & Vibrations

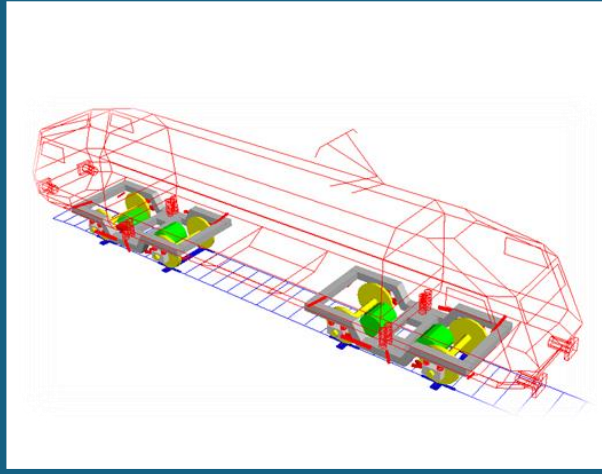
## Digital Twins Network



- » Vertical integration: Analysis of interaction between digital twins
- » Horizontal integration: System or component behaviour during all life cycle phases
- » Single point of truth: Consistent and continuous system data and models

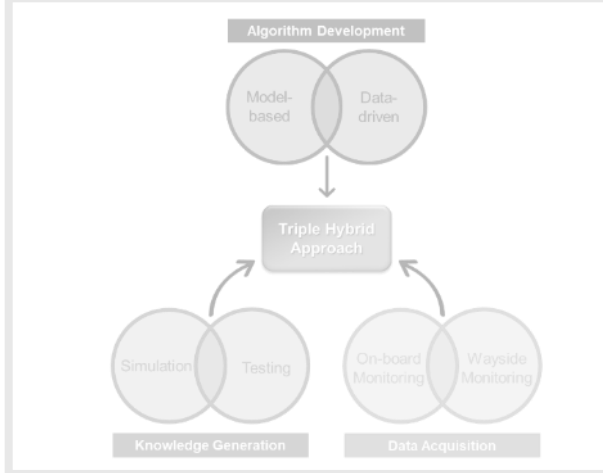
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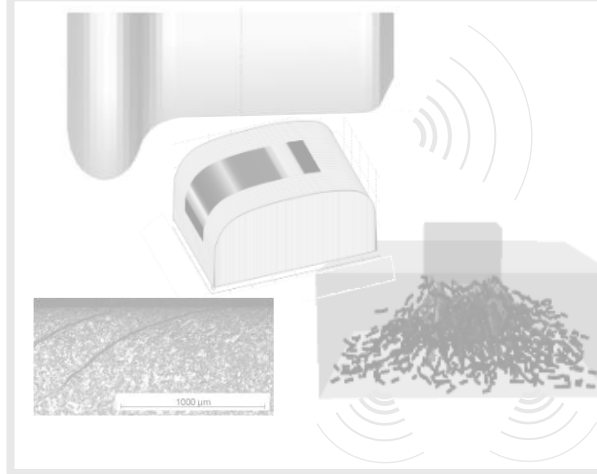
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# Vehicle Dynamics & Operation Analysis

Design

Homologation

Operation



## Probabilistic Design

- » Dimensioning of design parameters based on varying operating conditions



## Virtual Homologation

- » Methods for quantifying uncertainties in the model validation process
- » Automation of calculation methods for vehicle homologation
- » Methods for the parameterization of simulation models



## Operational Analysis

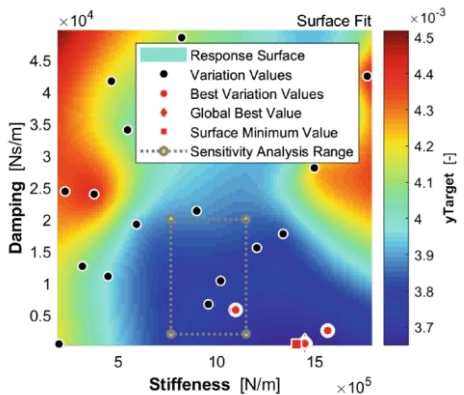
- » Description of operating conditions
- » Generation of load assumptions
- » Scenarios for virtual vehicle design

### Estimation of Dynamic Properties for the Validation of Driven Railway Vehicle Models

Josef Fuchs<sup>1</sup>(✉), Bernd Lubert<sup>1</sup>, Gabor Müller<sup>1</sup>, and Wolfgang Rulka<sup>2</sup>

<sup>1</sup> VIRTUAL VEHICLE Research Center, Graz, Austria  
josef.fuchs@v2c2.at

<sup>2</sup> Siemens Mobility GmbH, München, Germany



### Best Paper Award

#### Methodology to Gain Statistical Insights into the Effects of Operating Conditions on Railway Vehicle Dynamics

Anna Pichler<sup>1</sup>[0000-0002-7071-2703], Josef Fuchs<sup>1</sup>[0000-0001-6325-0080],  
Bernd Lubert<sup>1</sup>[0000-0003-4337-9826], and Florian Semrad<sup>2</sup>

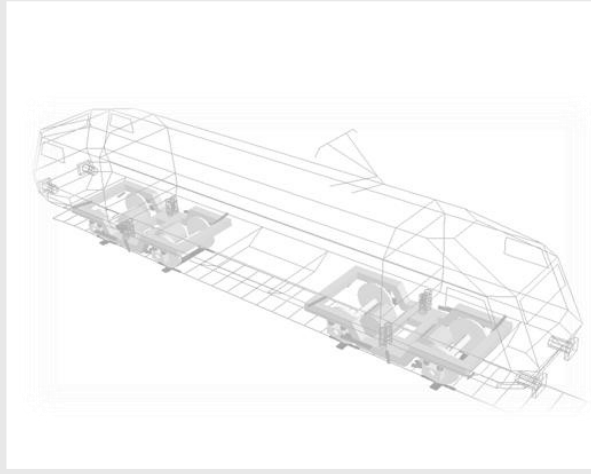
<sup>1</sup> Virtual Vehicle Research GmbH, Inffeldgasse 21a, 8010 Graz, Austria,  
✉ anna.pichler@v2c2.at, josef.fuchs@v2c2.at, bernd.lubert@v2c2.at,  
<sup>2</sup> Siemens Mobility Austria GmbH, Eggenberger Str. 31, 8020 Graz, Austria,  
florian.semrad@siemens.com

IAVSD  
2021

|                                  | Coefficient of friction $\mu_{exp}$ | Unb. lat. acceleration $a_y$ | Speed $v$ | Curvature $Ch$ | Superelevation $u$ | Alignment $\eta$ | Longitudinal level $z$ | Cross level $cl$ | Gauge $g$ | Twist $T_w$ |
|----------------------------------|-------------------------------------|------------------------------|-----------|----------------|--------------------|------------------|------------------------|------------------|-----------|-------------|
| Guiding force $Y$                | ●                                   | ●                            | ●         | ●              | ●                  | ○                | ○                      | ●                | ●         | ●           |
| Sum of guiding forces $\sum Y$   | ●                                   | ●                            | ●         | ●              | ●                  | ○                | ○                      | ●                | ●         | ●           |
| Wheel force $Q$                  | ○                                   | ●                            | ●         | ●              | ○                  | ○                | ○                      | ○                | ○         | ○           |
| Derailment coefficient $Y/Q$     | ●                                   | ●                            | ●         | ●              | ●                  | ○                | ○                      | ○                | ○         | ○           |
| Lat. axle box acc. $\ddot{y}$    | ○                                   | ○                            | ○         | ○              | ○                  | ○                | ○                      | ○                | ○         | ○           |
| Lat. car body acc. $\ddot{y}^*$  | -                                   | ○                            | ○         | ○              | ○                  | ○                | ○                      | ○                | ○         | ○           |
| Vert. axle box acc. $\ddot{z}$   | -                                   | -                            | ○         | ○              | ○                  | ○                | ○                      | ○                | ○         | ○           |
| Vert. car body acc. $\ddot{z}^*$ | -                                   | ○                            | ○         | ○              | ○                  | ○                | ○                      | ○                | ○         | ○           |

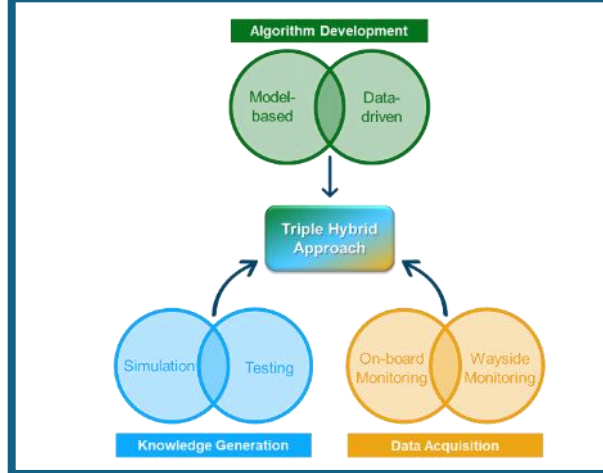
# Fields of Activity

## Vehicle Dynamics & Operation Analysis



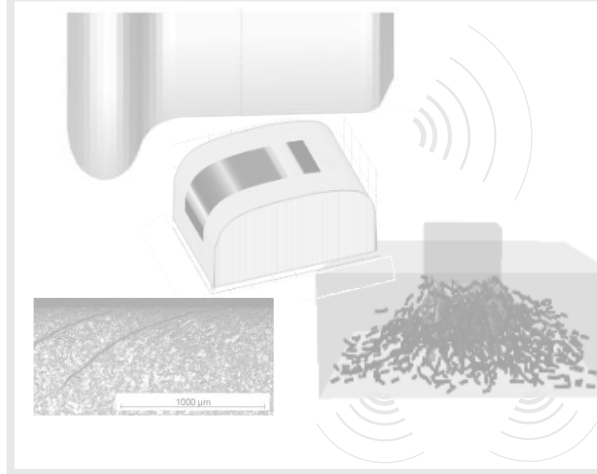
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# Monitoring & Diagnosis



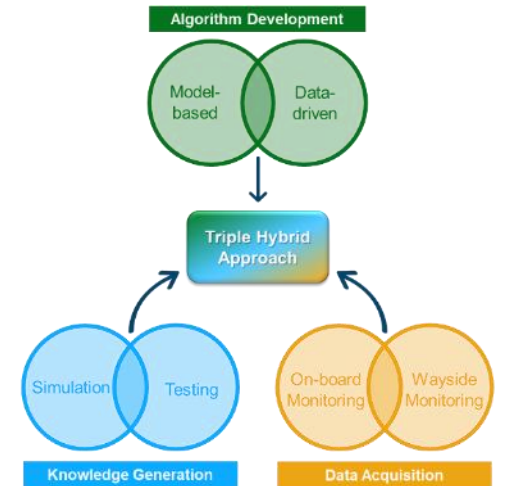
## Vehicle Monitoring

- » Monitoring of **bogie components**
- » **Sensor concepts** for component monitoring
- » Estimation of **operating conditions**
- » **Wheel flat detection**
- » **Wheel wear estimation**



## Algorithm Development

- » **Model-based methods** for monitoring of component states
- » **Data-driven methods** for high complex systems (ML / AI)



## Context-based Knowledge

- » Description and understanding of **physical effects** based on simulations and testing



## Data Acquisition



## Track Monitoring

- » Monitoring of **switch components**
- » Detection of **rail surface defects** (e.g. corrugation, squats)
- » Identification of **track parameters**
- » Anomaly detection & assessment of **track irregularities**



- » **Measurement equipment** for 'Proof-of-Concept' analysis (DataBeam)
- » Evaluation of innovative **sensor concepts**

# Monitoring & Diagnosis



Available online at [www.sciencedirect.com](http://www.sciencedirect.com)

ScienceDirect

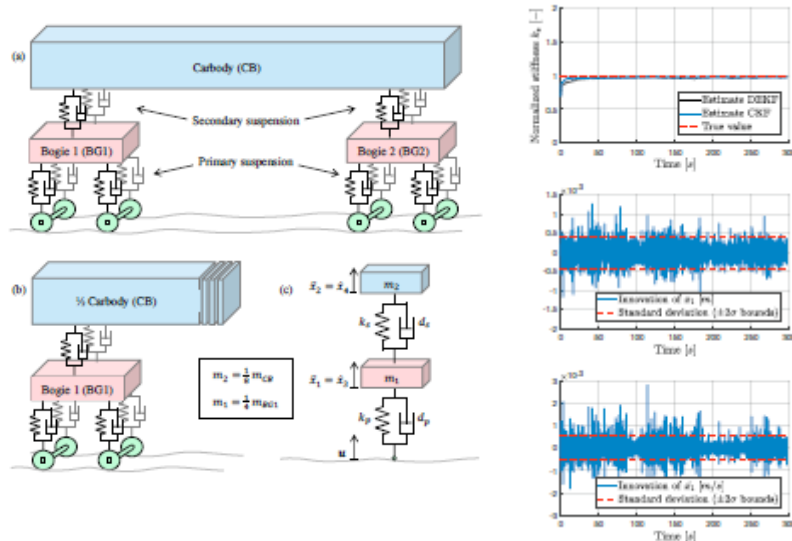
IFAC PapersOnLine 51-24 (2018) 1330–1335

IFAC Papers  
Online  
CONFERENCE PAPER ARCHIVE

## Railway Suspension System Fault Diagnosis using Cubature Kalman Filter Techniques

Selma Zoljic-Beglerovic<sup>\*,\*\*</sup> <sup>1</sup> Georg Stettinger<sup>\*</sup>  
Bernd Luber<sup>\*</sup> Martin Horn<sup>\*\*</sup>

<sup>\*</sup> VIRTUAL VEHICLE Research Center, Graz, Austria, (e-mail:  
{selma.zoljic-beglerovic; georg.stettinger; bernd.luber}@v2c2.at)  
<sup>\*\*</sup> Graz University of Technology, Institute of Automation and Control,  
Graz, Austria, (e-mail: martin.horn@tugraz.at)



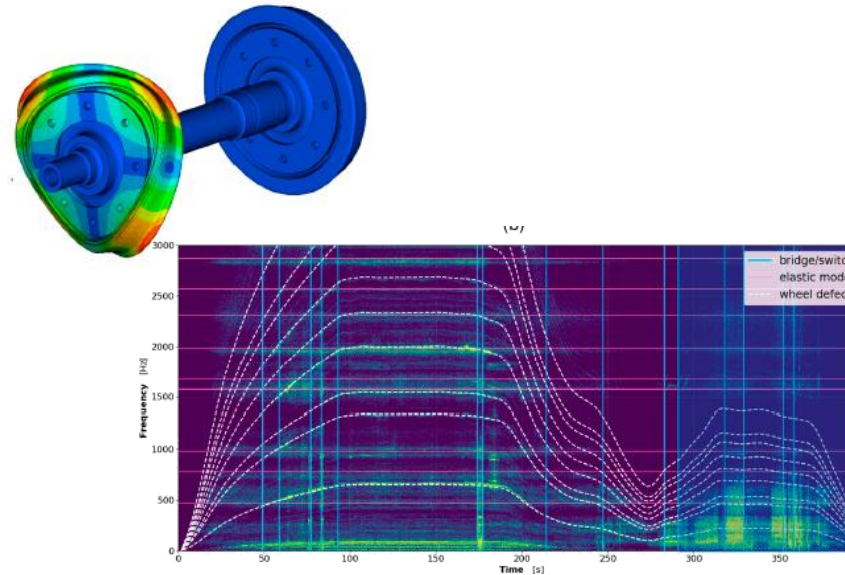
applied  
sciences

MDPI

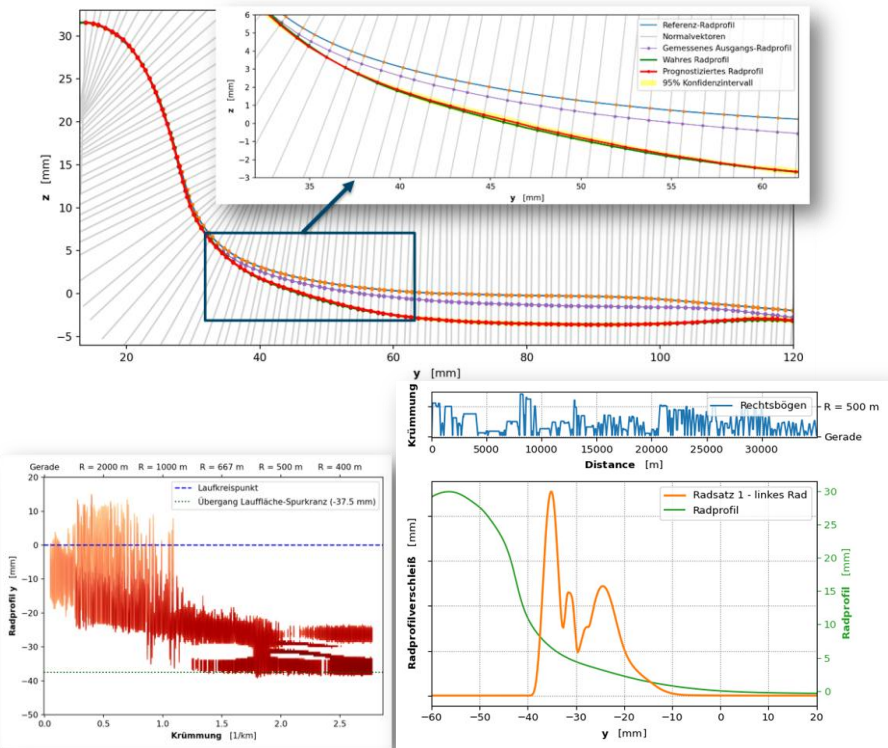
Article

## Methodology to Detect Rail Corrugation from Vehicle On-Board Measurements by Isolating Effects from Other Sources of Excitation

Anna De Rosa<sup>\*,</sup> Bernd Luber<sup>,</sup> Gabor Müller and Josef Fuchs<sup>,</sup>

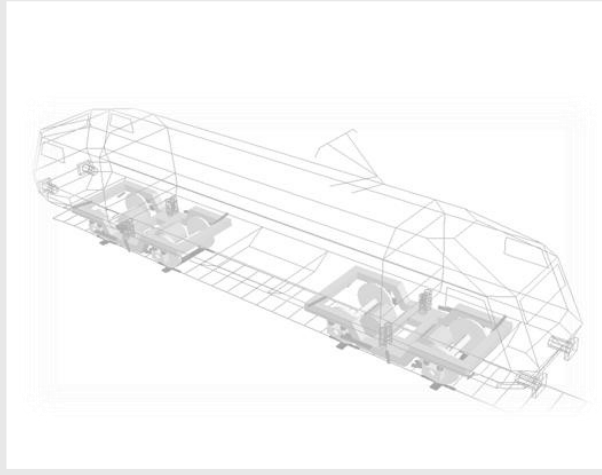


## Anforderungen an eine effiziente Radprofilprognose aus Sicht eines Digitalen Zwillings



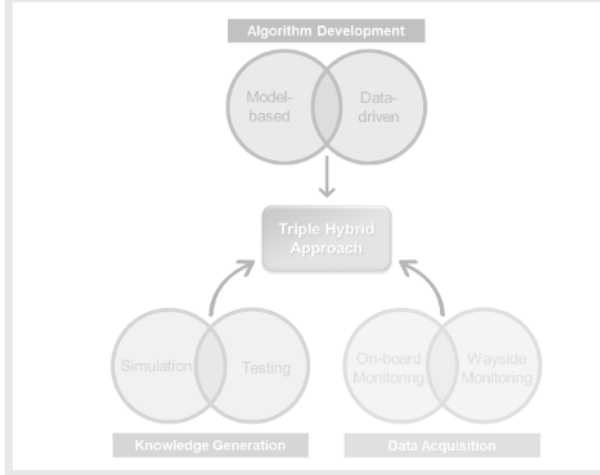
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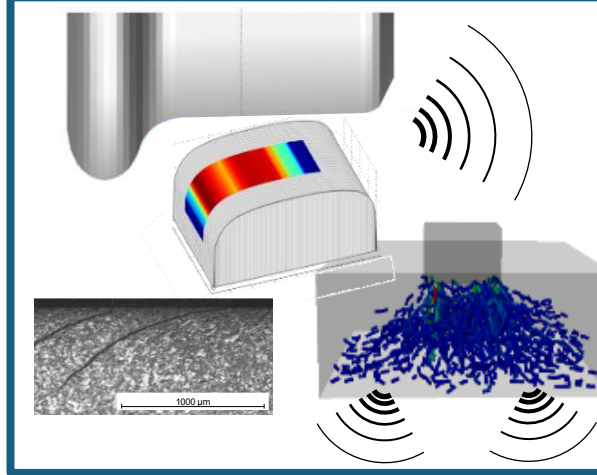
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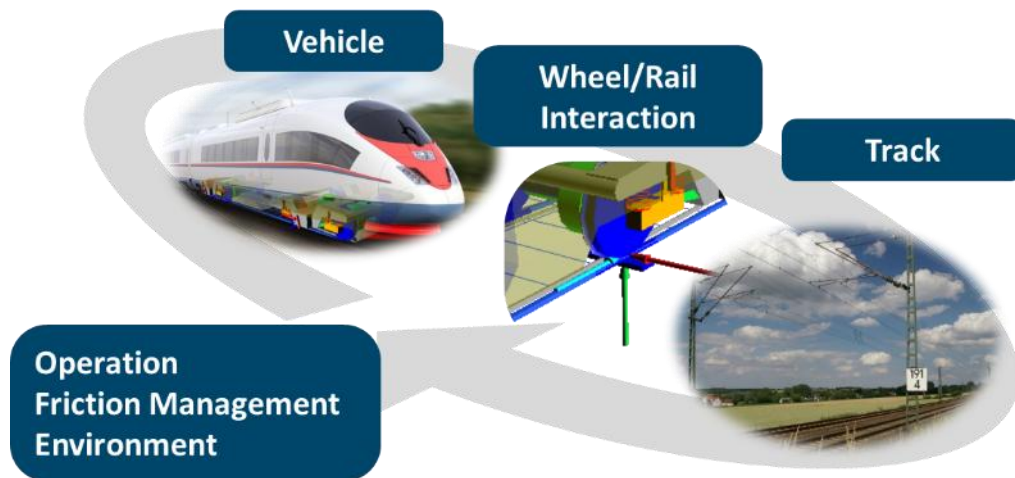
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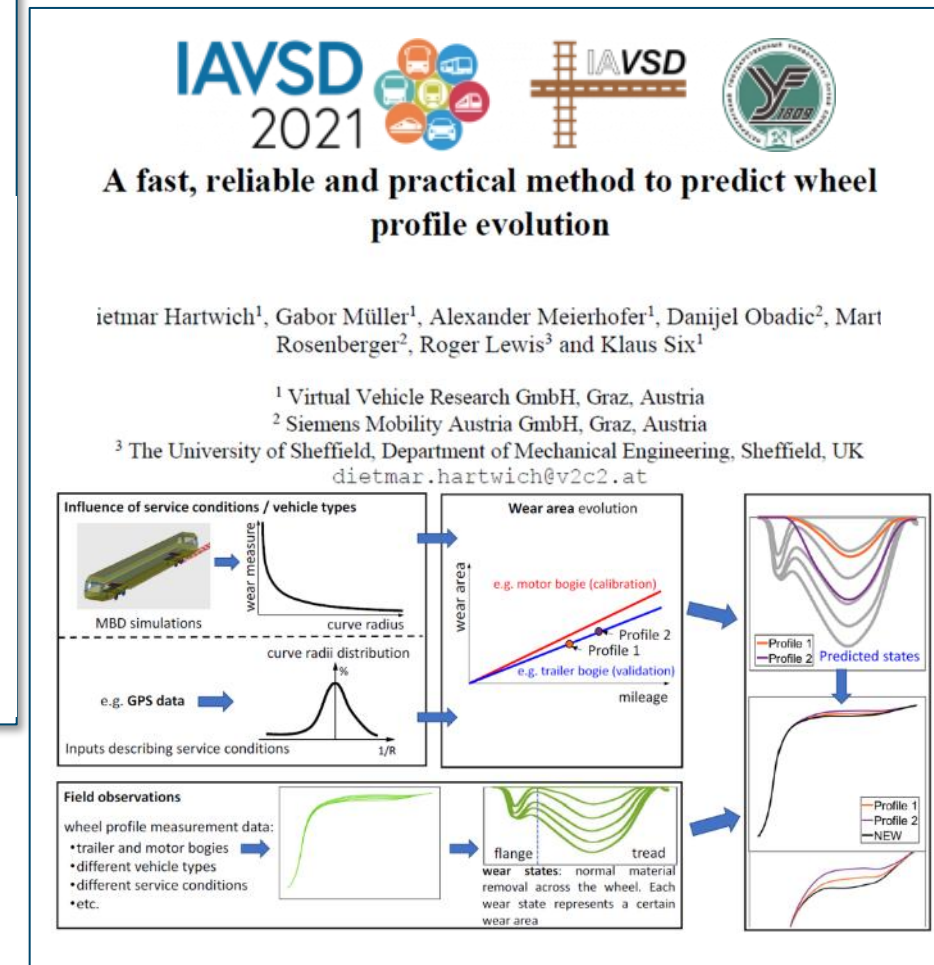
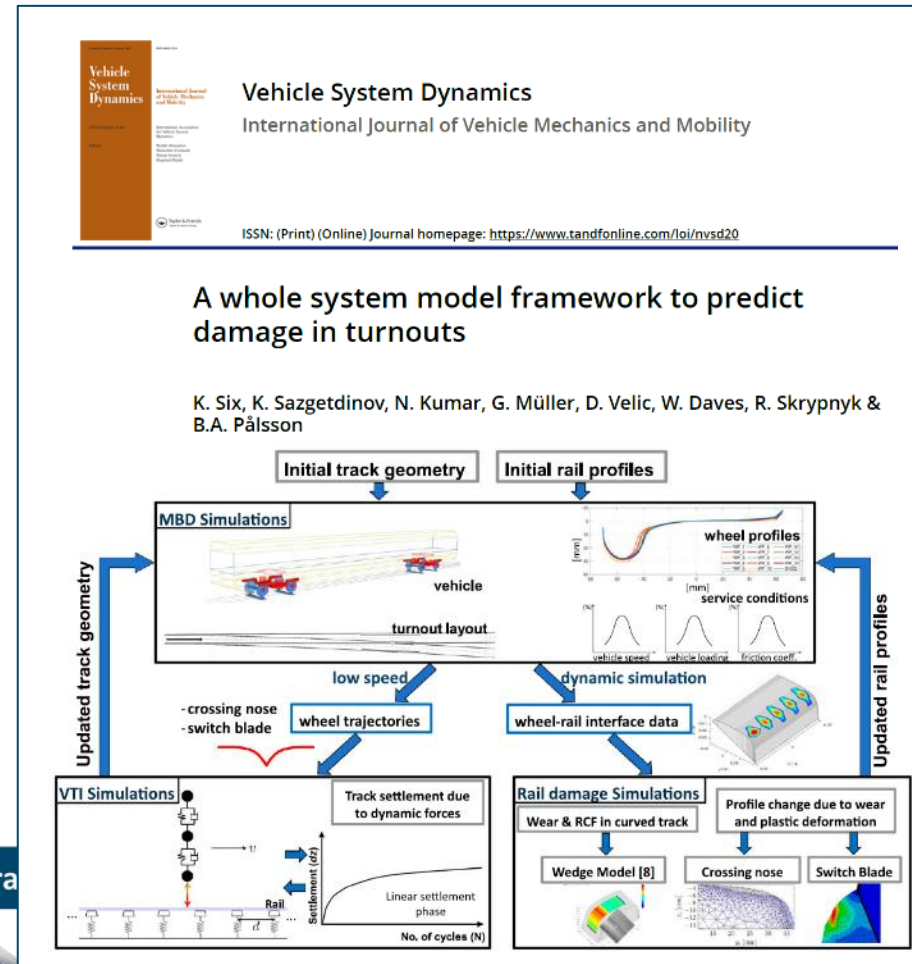


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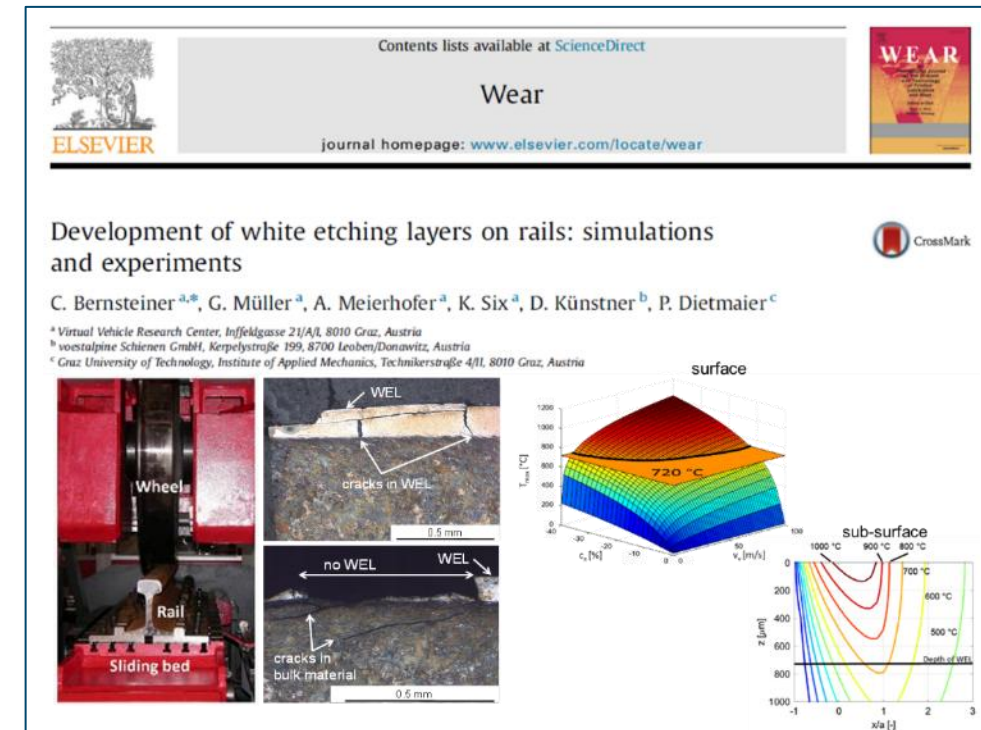
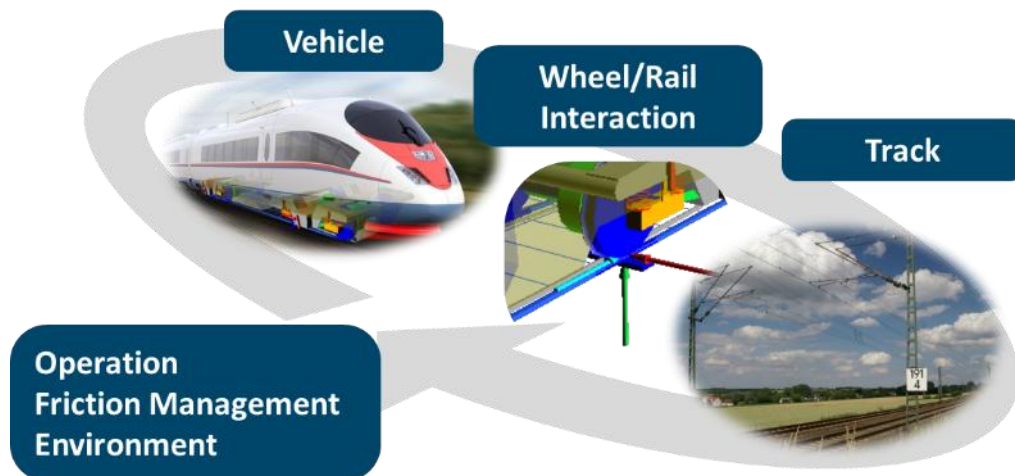
# Wheel-Rail Interaction & Deterioration Phenomena



## Damage & Deterioration

- RCF
- Wear
- Track settlement

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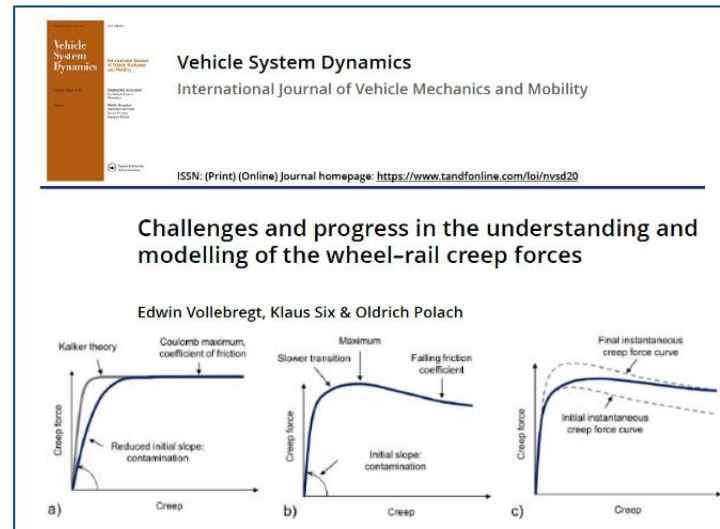
## Material Modelling

- Severe plastic deformation
- Thermal phase change
- Ballast behaviour

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## Wheel-Rail Contact

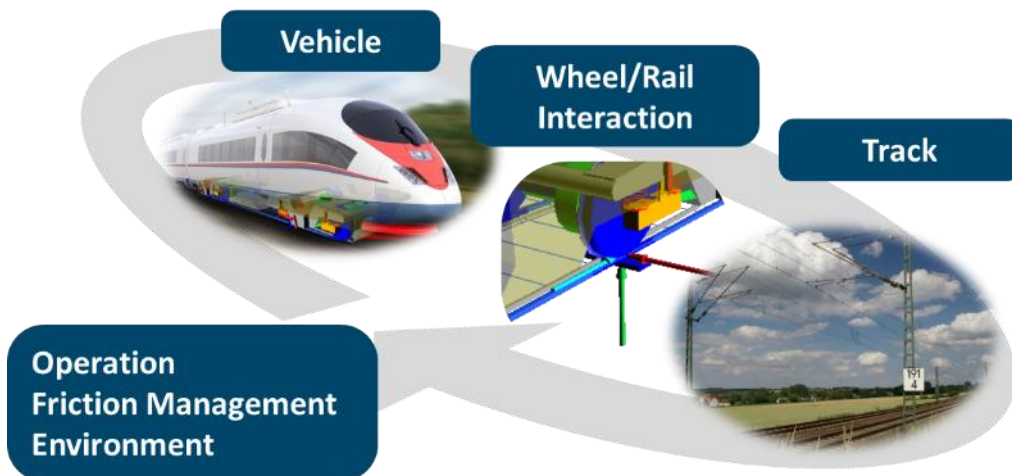
- Normal contact
- Adhesion
- 3<sup>rd</sup> Body Layer

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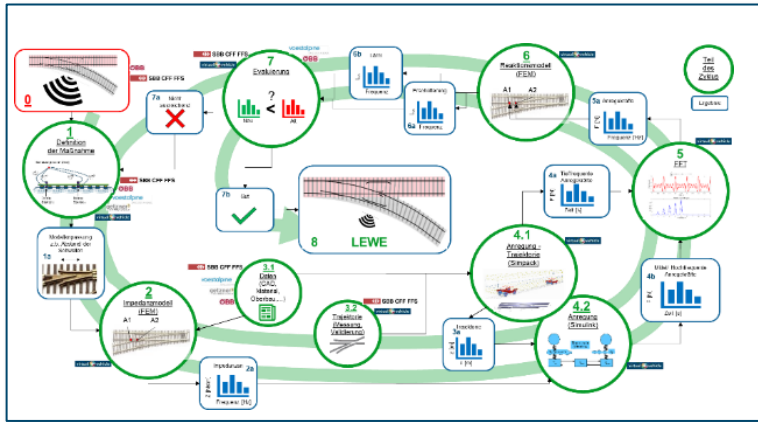
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# Wheel-Rail Interaction & Deterioration Phenomena



## Noise & Vibrations

- Modular approach
- Combination of sub-modules to describe complex situations

## Wheel-Rail Contact

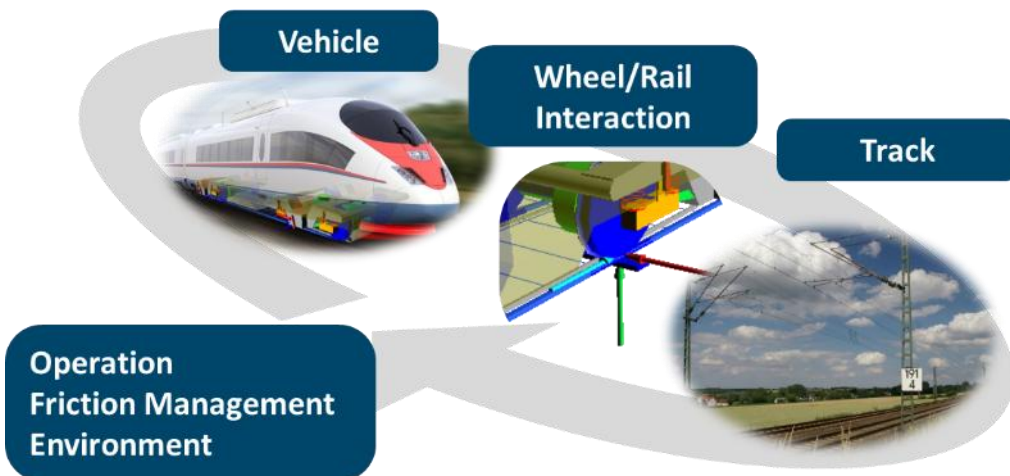
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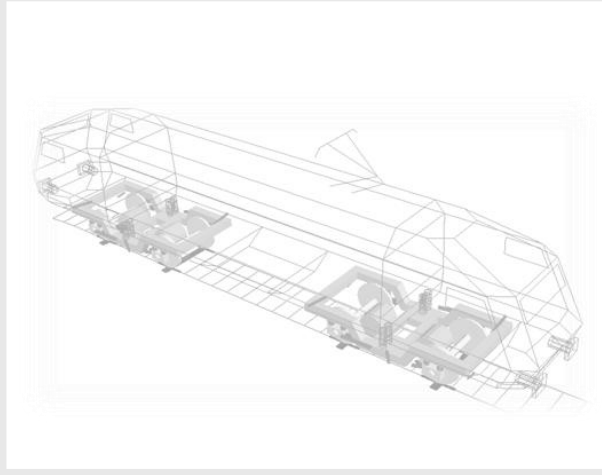
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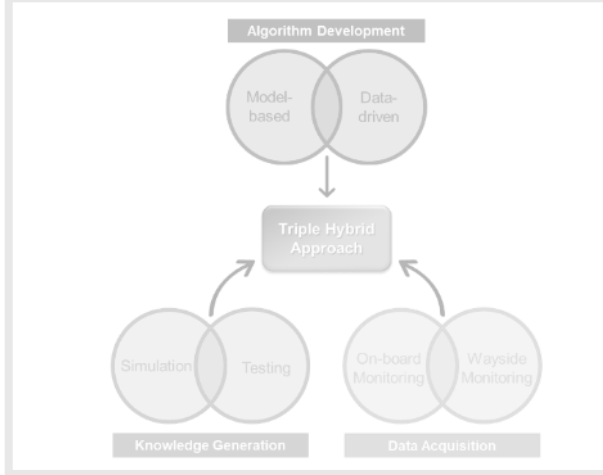
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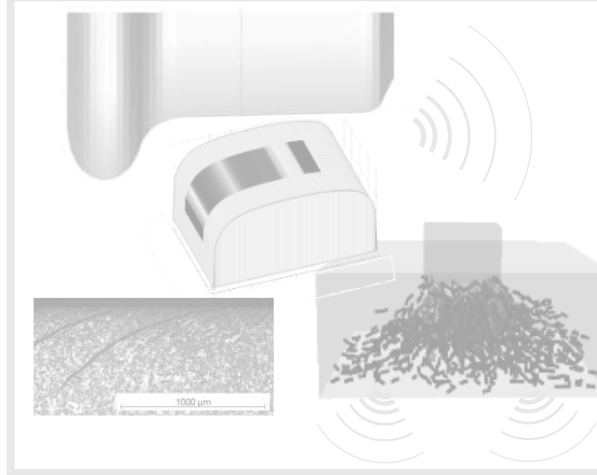
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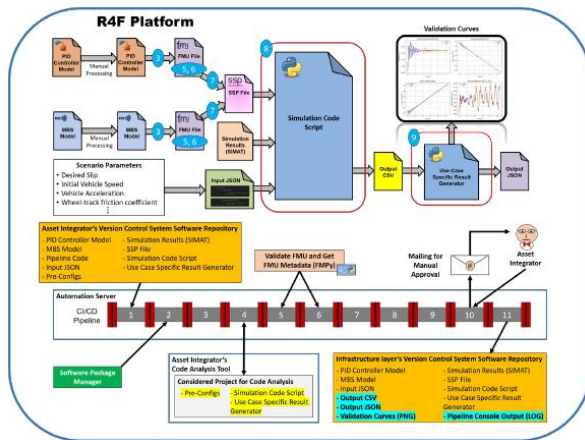
# Digital Twins Network

## Pipeline-based Automated Integration and Delivery Testing of Simulation Assets with FMI/SSP in a Railway Digital Twin

Ozan Kugu<sup>1</sup> Shiyang Zhou<sup>1</sup> Stefan H. Reiterer<sup>2</sup> Mario Schwaiger<sup>2</sup> Lukas Wurth<sup>1</sup> Manfred  
Grafinger<sup>1</sup>

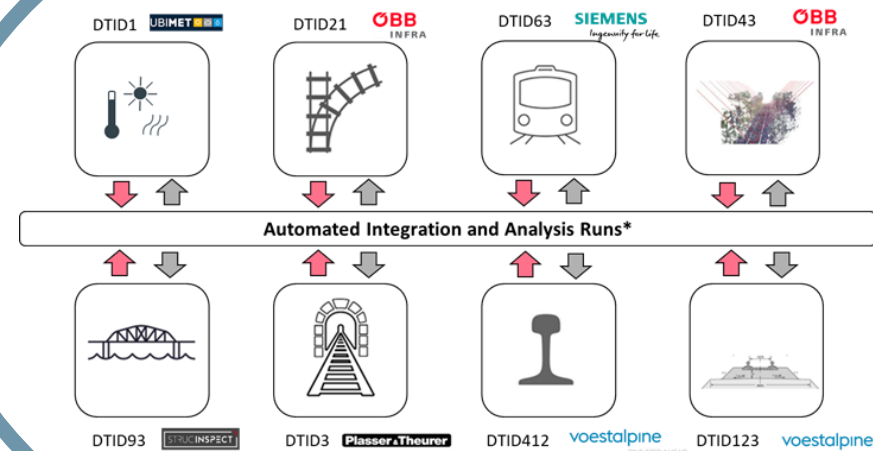
<sup>1</sup>Institute of Engineering Design and Product Development, TU Wien, 1060 Vienna, Austria, ozan.kugu@tuwien.ac.at

<sup>2</sup>Virtual Vehicle Research GmbH, 8010 Graz, Austria, stefan.reiterer@v2c2.at



 **Vertical integration**

- » Analysis of interaction between digital twins



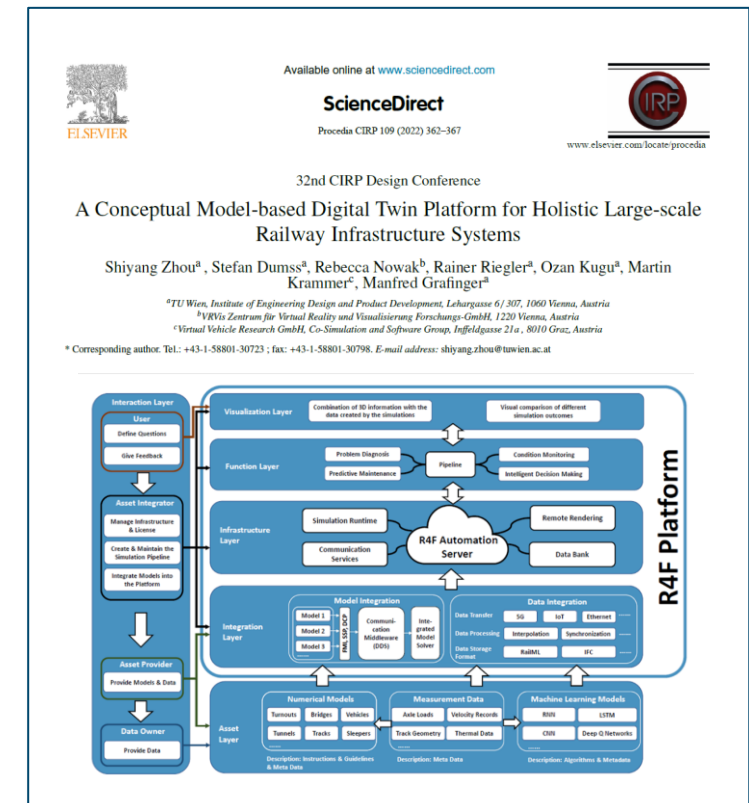
 **Horizontal integration**

- » System or component behavior during all life cycle phases



### Single point of truth

- » Consistent and continuous system data and models



# Key partners and associations

## KEY PARTNERS

**voestalpine**

EINEN SCHRITT VORAUS.

**SIEMENS**

*Ingenuity for life*



**SBB CFF FFS**

## SCIENCE



**University of Sheffield**



**BRNO UNIVERSITY OF TECHNOLOGY**

## INDUSTRY

**ALSTOM**

**CAF**



**KNORR-BREMSE**

**LB Foster**

**STADLER**

**RAILplus**

**Plasser & Theurer**

**LUCCHINI RS GROUP**

**getzner**

 **Thank You**  
**For Your Attention**

## Contact us:



**JOSEF FUCHS**

Team Leader Rail System

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 : +43 664 88371330

 : josef.fuchs@v2c2.at